

Contents

Preface XV

List of Contributors XVII

1	Implantable Bioelectronics – Editorial Introduction	1
	<i>Evgeny Katz</i>	
	References	5
2	Magnetically Functionalized Cells: Fabrication, Characterization, and Biomedical Applications	7
	<i>Ekaterina A. Naumenko, Maria R. Dzamukova, and Rawil F. Fakhrullin</i>	
2.1	Introduction	7
2.2	Magnetic Microbial Cells	8
2.2.1	Direct Deposition of MNPs onto Microbial Cells	8
2.2.2	Polymer-Mediated Deposition of MNPs onto Microbial Cells	9
2.2.2.1	Layer-by-Layer Magnetic Functionalization of Microbial Cells	9
2.2.2.2	Single-step Polymer-mediated Magnetic Functionalization of Microbial Cells	11
2.2.3	Applications of Magnetically Modified Microbial Cells	15
2.2.3.1	Biosorbents and Biocatalysts	15
2.2.3.2	Whole-Cell Biosensors and Microfluidic Devices	15
2.2.3.3	Remotely Controlled Organisms	16
2.3	Magnetic Labeling of Mammal (Human) Cells	18
2.3.1	Intracellular Labeling of Cells	18
2.3.1.1	Labeling with Anionic Magnetic Nanoparticles	18
2.3.1.2	Labeling with Cationic Magnetic Nanoparticles	19
2.3.2	Extracellular Labeling of Cells	20
2.3.3	Applications of Magnetically Labeled Cells in Biomedicine	20
2.3.3.1	MRI Imaging of MNPs-Labeled Cells	21
2.3.3.2	MNPs-Mediated Cell Delivery and Tissue Engineering	21

2.4	Conclusion	23
	Acknowledgment	23
	References	23
3	Untethered Insect Interfaces	27
	<i>Amol Jadhav, Michel M. Maharbiz, and Hirotaka Sato</i>	
3.1	Introduction	27
3.2	Systems for Tetherless Insect Flight Control	30
3.2.1	Various Approaches to Tetherless Flight Control	30
3.2.2	Neurostimulation for Initiation of Wing Oscillations	30
3.2.3	Extracellular Stimulation of the Muscles to Elicit Turns	32
3.3	Implantable Bioelectronics in Insects	33
3.3.1	Example: Insertion of Flexible Substrates into the Developing Eye	33
3.4	Conclusions	39
	References	39
4	Miniaturized Biomedical Implantable Devices	45
	<i>Ada S.Y. Poon</i>	
4.1	Introduction	45
4.2	Energy Harvesting as a Pathway to Miniaturization	47
4.3	Implementation of Implantable Devices	48
4.3.1	RF Power Harvesting	49
4.3.1.1	Matching Network	49
4.3.1.2	Rectifier	49
4.3.1.3	Regulator and Bandgap Reference	50
4.3.1.4	Low-Power Controller and Auxiliary Circuits in the Implant Functional Block	50
4.3.2	Wireless Communication Link	51
4.3.2.1	Forward Data Link	51
4.3.2.2	Reverse Data Link	54
4.3.3	Payload and Applications: Locomotive Implant and Implantable Cardiac Probe	56
4.3.3.1	Actuation for Therapeutics: Millimeter-Sized Wirelessly Powered and Remotely Controlled Locomotive Implant	56
4.3.3.2	Low-Power Sensing for Diagnostics: Implantable Intracardiac Probe	59
4.4	Conclusion	62
	References	62
5	Cross-Hierarchy Design Exploration for Implantable Electronics	65
	<i>Mrigank Sharad and Kaushik Roy</i>	
5.1	Introduction	65
5.2	System Overview of a Generic Bioelectronic Implant	65
5.3	Circuit Design for Low-Power Signal Processing	67
5.3.1	Design Challenges for Low-Power Bioelectronic Sensor Interface	67

5.3.2	Analog Signal Processing Using Subthreshold Circuits	68
5.3.3	Analog-to-Digital Conversion	69
5.3.4	Low-Power Digital Signal Processing	71
5.3.4.1	V_{DD} Scaling and Parallel Processing	71
5.3.4.2	Dynamic Voltage and Frequency Scaling	72
5.3.4.3	Standby Mode Power Reduction	73
5.3.4.4	Minimum Energy Subthreshold Operation	73
5.3.5	FinFETs for Ultralow Voltage Subthreshold Circuits	74
5.4	Architecture-Level Optimizations for Low-Power Data Processing	76
5.4.1	Optimal Apportioning of Computation Task to Analog and Digital Blocks	76
5.4.2	Approximate Computing for Low Power	78
5.5	Design of Energy-Efficient Memory	79
5.5.1	Design Challenges with Subthreshold SRAM	79
5.5.1.1	On-Current to Off-Current Ratio	79
5.5.1.2	Sizing Constraints	79
5.5.1.3	Variability	80
5.5.2	Spin Transfer Torque MRAM (STT-MRAM) for Energy-Efficient Memory Design	80
5.6	Wireless Communication Power Delivery	81
5.6.1	Near-Field Electromagnetic Wireless Communication	82
5.6.2	Far-Field Electromagnetic Wireless Communication	82
5.6.3	Wireless Energy Transfer	83
5.7	Conclusion	83
	References	84
6	Neural Interfaces: from Human Nerves to Electronics	87
	<i>Jessica D. Falcone, Joav Birjiniuk, Robert Kretschmar, and Ravi V. Bellamkonda</i>	
6.1	Introduction	87
6.2	Fusing Robotics with the Human Body: Interfacing with the Peripheral Nervous System	87
6.2.1	The Anatomy of Peripheral Nerves	88
6.2.1.1	Glial Cells of the Peripheral Nervous System	88
6.2.1.2	Functional Afferent and Efferent Pathways	88
6.2.2	Interfacing with the Periphery for Recording and Stimulation	89
6.2.2.1	Noninvasive Electrodes	89
6.2.2.2	Extraneural Electrodes	90
6.2.2.3	Intrafascicular Electrodes	91
6.2.2.4	Regeneration-Based Electrodes	92
6.2.2.5	Research Designs and Challenges	92
6.3	Listening to the Brain: Interfacing with the Central Nervous System	93
6.3.1	Glial Cells of the Central Nervous System	93
6.3.1.1	Microglia – Sentinels of the Brain	93

6.3.1.2	Astrocytes – Cellular Support for Neurons	94
6.3.2	Interfacing with the Brain for Recordings	94
6.3.2.1	Noninvasive Electrodes	94
6.3.2.2	Extracortical Electrodes	95
6.3.2.3	Invasive Intracortical Electrodes	95
6.3.2.4	Research Designs and Challenges	97
6.4	Electrical Modulation of the Human Nervous System: Stimulation and Clinical Applications	99
6.4.1	Deep Brain Stimulation	100
6.4.1.1	Biological Mechanisms	100
6.4.1.2	Electrode Design and Stimulation	100
6.4.1.3	Research Designs and Challenges	101
6.4.2	Electrical Modulation of Nerve Regeneration	101
6.4.2.1	Biological Mechanisms	102
6.4.2.2	Electrode Stimulation	102
6.4.3	Pain Modulation	102
6.4.3.1	Biological Mechanisms	102
6.4.3.2	Clinical Outcomes	103
6.4.4	Electrical Modulation of Inflammation	103
6.4.4.1	The Vagus Nerve and Stimulation	103
6.4.4.2	Cholinergic Anti-Inflammatory Pathway	104
6.5	Future Directions for Neural Interfacing	105
	References	106
7	Cyborgs – the Neuro-Tech Version	115
	<i>Kevin Warwick</i>	
7.1	Introduction	115
7.2	Biological Brains in a Robot Body	116
7.3	Deep Brain Stimulation	120
7.4	General Purpose Brain Implants	123
7.5	Noninvasive Brain-Computer Interfaces	126
7.6	Subdermal Magnetic Implants	127
7.7	RFID Implants	128
7.8	Conclusions	130
	References	131
8	Interaction with Implanted Devices through Implanted User Interfaces	133
	<i>Christian Holz, Tovi Grossman, George Fitzmaurice, and Anne Agur</i>	
8.1	Implanted User Interfaces	135
8.1.1	Design Considerations	136
8.1.1.1	Input through Implanted Interfaces	136
8.1.1.2	Output through Implanted Interfaces	136
8.1.1.3	Communication and Synchronization	137
8.1.1.4	Power Supply through Implanted Interfaces	137

8.1.2	Summary	137
8.2	Evaluating Basic Implanted User Interfaces	137
8.2.1	Devices	138
8.2.2	Experimenters	139
8.2.3	Procedure	139
8.2.4	Medical Procedure	139
8.2.5	Study Procedure and Results	140
8.2.5.1	Touch Input Device (Pressure Sensor, Tap Sensor, Button)	140
8.2.5.2	Hover Input Device (Capacitive and Brightness Sensor)	141
8.2.5.3	Output Device (Red LED, Vibration Motor)	142
8.2.5.4	Audio Device (Speaker and Microphone)	144
8.2.5.5	Powering Device (Powermat Wireless Charger)	145
8.2.5.6	Wireless Communication Device (Bluetooth Chip)	146
8.2.6	Discussion	147
8.2.7	Exploring Exposed Components	147
8.3	Qualitative Evaluation	148
8.3.1	Simulating Implants: Artificial Skin	148
8.3.2	Task and Procedure	149
8.3.3	Participants	150
8.3.4	Results	150
8.4	Medical Considerations	150
8.4.1	Location	150
8.4.2	Device Parameters	151
8.4.3	Risks	151
8.4.4	Implications and Future Studies	152
8.5	Discussion and Limitations	152
8.5.1	Study Limitations	152
8.6	Conclusions	153
	References	153
9	Ultralow Power and Robust On-Chip Digital Signal Processing for Closed-Loop Neuro-Prosthesis	155
	<i>Swarup Bhunia, Abhishek Basak, Seetharam Narasimhan, and Maryam Sadat Hashemian</i>	
9.1	Introduction	155
9.1.1	Neural Interfaces	158
9.1.2	Closing the Neural Loop: Significance of On-Chip DSP	160
9.2	Algorithm: a Vocabulary-Based Neural Signal	162
9.2.1	Analysis	162
9.2.2	Spike-Level Vocabulary	163
9.2.3	Spike Detection	164
9.2.4	Spike Characterization and Sorting	166
9.2.5	Burst-Level Vocabulary	167
9.2.6	Multichannel Vocabulary for Behavior-Specific Patterns	167
9.2.7	Output Packet Generation	169

9.3	Hardware Implementation	171
9.3.1	Wavelet Module	173
9.3.1.1	Vocabulary Module	177
9.3.2	Area, Power Reduction Methodologies	179
9.3.2.1	Subthreshold versus Super-Threshold Operation	181
9.3.3	Impact of Process Variations on Yield	183
9.3.3.1	Preferential Design	185
9.3.4	Overall Design Flow	188
9.4	Summary	191
	References	191
10	Implantable CMOS Imaging Devices	195
	<i>Jun Ohta</i>	
10.1	Introduction	195
10.2	Fundamentals of CMOS Imaging Devices	198
10.2.1	Photosensors	198
10.2.2	Active Pixel Sensor	199
10.2.3	Log Sensor	201
10.2.4	Pulse Width Modulation Sensor	202
10.2.5	SPAD Sensor	203
10.3	Artificial Retina	203
10.3.1	Principle of Artificial Retina	203
10.3.2	Artificial Retina Based on CMOS Imaging Device	204
10.4	Brain-Implantable CMOS Imaging Device	210
10.4.1	Measurement Methods for Brain Activities	210
10.4.2	Fiber Endoscope and Head-Mountable Device	211
10.4.3	Brain-Implantable CMOS Imaging Device	212
10.5	Summary and Future Directions	215
	Acknowledgments	217
	References	217
11	Implanted Wireless Biotelemetry	221
	<i>Mehmet Rasit Yuce and Jean-Michel Redoute</i>	
11.1	Introduction	221
11.2	Biotelemetry	223
11.2.1	Inductive Link for Forward Data	225
11.2.2	Wireless Power Link	226
11.2.3	Implantable Telemetry Links	228
11.2.3.1	Wideband Telemetry Link	228
11.2.3.2	Multichannel Neural Recording Systems	228
11.2.3.3	Wireless Endoscope	230
11.3	Microelectrode Arrays and Interface Electronics	232
11.3.1	Stimulation Front Ends	233
11.3.2	Recording Front-Ends	238

11.3.2.1	Instrumentation Amplifier	239
11.4	Conclusion	242
	References	242
12	Nano-Enabled Implantable Device for <i>In Vivo</i> Glucose Monitoring	247
	<i>Esteve Juanola-Feliu, Jordi Colomer-Farrarons, Pere Miribel-Catalá, Manel González-Piñero, and Josep Samitier</i>	
12.1	Introduction	247
12.1.1	Nanotechnology	247
12.1.2	Nanomedicine	248
12.2	Biomedical Devices for <i>In Vivo</i> Analysis	249
12.2.1	State of the Art	249
12.2.2	The Innovative Biomedical Device	250
12.2.3	Architecture of the Implantable Device	251
12.2.4	Implantable Front-End Architecture for <i>In Vivo</i> Detection Biosensor Applications	254
12.2.4.1	Architecture of the Envisaged Subcutaneous Device	254
12.2.4.2	Implementation and Results	258
12.2.5	The Diabetes Care Devices Market	260
12.3	Conclusions and Final Recommendations	261
	References	262
13	Improving the Biocompatibility of Implantable Bioelectronics Devices	265
	<i>Gymama Slaughter</i>	
13.1	Introduction	265
13.2	Implantable Bioelectronic Device Materials	267
13.3	Surface Composition	269
13.4	Response to Implantation	273
13.5	Conclusion	278
	References	279
14	Abiotic (Nonenzymatic) Implantable Biofuel Cells	285
	<i>Sven Kerzenmacher</i>	
14.1	Introduction	285
14.1.1	The History of Implantable Abiotic Fuel Cells	285
14.2	Basic Principles	286
14.2.1	Electrode Reactions and Theoretical Potentials	287
14.2.2	Practical Fuel Cell Voltage, Power Density, and Efficiency	289
14.2.3	Reliable Characterization of Implantable Glucose Fuel Cells	291
14.3	Abiotic Catalyst Materials and Separator Membranes	292
14.3.1	Electrocatalysts for Glucose Oxidation	292
14.3.2	Electrocatalysts for Oxygen Reduction	293
14.3.3	Separator Membranes	294

14.4	Design Considerations	295
14.4.1	Site of Implantation	295
14.4.2	Strategies to Cope with the Presence of Mixed Reactants	297
14.5	State-of-the-Art and Practical Examples	299
14.5.1	Comparison of Fuel Cell Designs and Their Power Densities	299
14.5.2	Factors Affecting Long-Term Operation	304
14.6	Conclusion and Outlook	307
14.6.1	State-of the-Art	307
14.6.2	Applications	308
14.6.3	Challenges and Future Trends	309
	References	309
15	Direct-Electron-Transfer-Based Enzymatic Fuel Cells <i>In Vitro</i>, <i>Ex Vivo</i>, and <i>In Vivo</i>	315
	<i>Magnus Falk, Dmitry Pankratov, Zoltan Blum, and Sergey Shleev</i>	
15.1	Introduction	315
15.2	Oxidoreductases for Direct-Electron-Transfer-Based Biodevices	316
15.2.1	Anodic Bioelements	317
15.2.2	Cathodic Bioelements	321
15.3	Design of Enzyme-Based Biodevices	323
15.3.1	Electrode Material	325
15.3.2	Electrode Function	327
15.4	Examples of Direct Electron Transfer Enzymatic Fuel Cells	329
15.4.1	Enzymatic Fuel Cells Operating <i>In Vitro</i>	329
15.4.2	Biodevices Operating <i>In Vivo</i>	334
15.4.3	Enzymatic Fuel Cells Operating <i>Ex Vivo</i>	336
15.4.4	Summary	339
15.5	Outlook	340
	References	341
16	Enzymatic Fuel Cells: From Design to Implantation in Mammals	347
	<i>Serge Cosnier, Alan Le Goff, and Michael Holzinger</i>	
16.1	Introduction	347
16.2	Design of Implantable Bioelectrodes of Glucose Biofuel Cells	352
16.3	Packaging of Implanted Biofuel Cells	356
16.4	Surgery	358
16.5	Implanted Biofuel Cell Performances	359
	References	361
17	Implanted Biofuel Cells Operating <i>In Vivo</i>	363
	<i>Evgeny Katz</i>	
17.1	Implanted Biofuel Cells	363
	Acknowledgment	377
	References	377

18	Biomedical Implantable Systems – History, Design, and Trends	381
	<i>Wen H. Ko and Philip X.-L. Feng</i>	
18.1	Introduction	381
18.2	History: Review of Implant Systems	383
18.2.1	Historical Review of Early Implant Systems, 1950–1970	384
18.2.1.1	Historical Review of Early Implant <i>Telemetry</i> Systems, 1950–1970	384
18.2.1.2	Historical Review of Early Implant <i>Stimulation</i> Systems, 1950–1970	391
18.2.1.3	Historical Review of Early Implant <i>Control</i> Systems, 1950–1970	391
18.2.2	Historical Review of Implant Systems – 1970–1990	394
18.2.3	Historical Review of Implant Systems – 1990–2012	395
18.3	Design of Implant Systems	396
18.3.1	Basic Considerations and Characteristics of RF MEMS Implantable Systems	397
18.3.1.1	Legal Considerations of the Radio Frequency (RF), Field Strength, and Power Levels	397
18.3.1.2	Biocompatibility and Protection of the Biomedical Implant Systems	398
18.3.1.3	Characteristics of Biological and Medical Signals	399
18.3.2	Design Considerations of Implantable Systems	400
18.3.3	Micropower Electronic Design Approaches and Samples	401
18.3.4	Power Supply Design	403
18.3.5	System Integration and Micro-Packaging	404
18.4	Present Challenges	405
18.5	Future Trends	406
	Acknowledgments	407
	References	407
19	Brain–Computer Interfaces: Ethical and Policy Considerations	411
	<i>Ellen M. McGee</i>	
19.1	Introduction	411
19.2	Neuroethics	412
19.3	Brain–Computer Interfaces	412
19.4	Noninvasive Interfaces	413
19.5	Partially Invasive Interfaces	413
19.6	Invasive Interfaces	413
19.7	Development of Brain–Computer Interfaces	414
19.8	Therapy/Enhancement	418
19.9	Ethical Issues	419
19.10	Brain Chips and Cloning	420
19.11	Regulatory Procedures	424
19.12	Principles and Standards for Adoption	426
	References	430

20	Conclusions and Perspectives	435
	<i>Evgeny Katz</i>	
	References	436
	Index	437