

Contents

Part I: Self-Organizing Swarm Robotic Systems

Morphogenetic Robotics - An Evolutionary Developmental Approach to Morphological and Neural Self-Organization of Robotic Systems	3
<i>Yaochu Jin, Yan Meng</i>	
How to Engineer Robotic Organisms and Swarms?	25
<i>Thomas Schmickl</i>	
Flocking Control Algorithms for Multiple Agents in Cluttered and Noisy Environments	53
<i>Hung Manh La, Weihua Sheng</i>	
Genetic Stigmergy	81
<i>Joshua Brandoff, Hiroki Sayama</i>	
From Ants to Robots and Back: How Robotics Can Contribute to the Study of Collective Animal Behavior	105
<i>Simon Garnier</i>	

Part II: Self-Reconfigurable Modular Robots

On Self-Optimized Self-Assembling of Heterogeneous Multi-robot Organisms	123
<i>Serge Kernbach, Benjamin Girault, Olga Kernbach</i>	
Morphogenetic Self-Reconfiguration of Modular Robots	143
<i>Yan Meng, Yaochu Jin</i>	

Basic Problems in Self-Assembling Robots and a Case Study of Segregation on Tribolon Platform	173
<i>Shuhei Miyashita, Aubery Marchel Tientcheu Ngouabeu, Rudolf M. F��chslin, Kohei Nakajima, Christof Audretsch, Rolf Pfeifer</i>	

Part III: Autonomous Mental Development in Robotic Systems

Brain Like Temporal Processing	195
<i>Juyang Weng</i>	

Part IV: Special Applications

Towards <i>Physarum</i> Robots	215
<i>Jeff Jones, Soichiro Tsuda, Andrew Adamatzky</i>	
Developing Self-Organizing Robotic Cells Using Organic Computing Principles.....	253
<i>Alwin Hoffmann, Florian Nafz, Andreas Schierl, Hella Seebach, Wolfgang Reif</i>	
Author Index	275